JAKA[®]

JAKA MiniCobo Collaborative Robot

Education Industry



400-006-2665

Email:marketing@jakarobotics.com





www.jakarobotics.com

Shanghai JAKA Robotics Ltd

- A Shanghai: Buildings 33-35, 610 Jianchuan Road, Minhang District, Shanghai
- A Changzhou: East Building, building 10, No. 377, Wuyi South Road, Wujin National High-tech Zone, Changzhou City, Jiangsu Province
- 🙎 Shenzhen: Room 501, Building 7, Taihua Wutong Industrial Park, Bao'an District, Shenzhen, Guangdong Province

Copyright © 2022 JAKA. All rights reserved.

JAKA Robotics holds the copyright to the contents of this catalogue. Copying or reproducing, in full or in part, may only be done with permission from JAKA. JAKA reserves the right to interpret and update the contents without notice.



Shanghai JAKA Robotics Ltd

Company Introduction

2014

JAKA Robotics Co-founded by engineers and roboticists

We understand that the pursuit of excellence requires searching high and low, far and wide, for new ideas and innovation. We named ourselves 'JAKA', which stands for Just Always Keep Amazing, in appreciation for our strive towards excellence.

JAKA Robotics is a high-tech company that focuses on innovative research, development and production of new generations of collaborative robots. It stands at the forefront of creating truly smart factories, meeting the requirements of industrial robotics while maintaining high levels of useability and simplicity. Our moto, 'Free Your Hands by JAKA', represents our drive to help companies, all over the world, automate all manner of tasks.

So far, JAKA has worked with more than 300 companies, from all over the world, across multiple industries, to provide automation solutions. In total, more than 10,000 JAKA cobots have already been deployed. Their flexibility and efficiency help those in the automobile, electronics and semi-conductor manufacturing industries, while their ease-of-use has made them accessible to those in education, commerce and new retail industries.

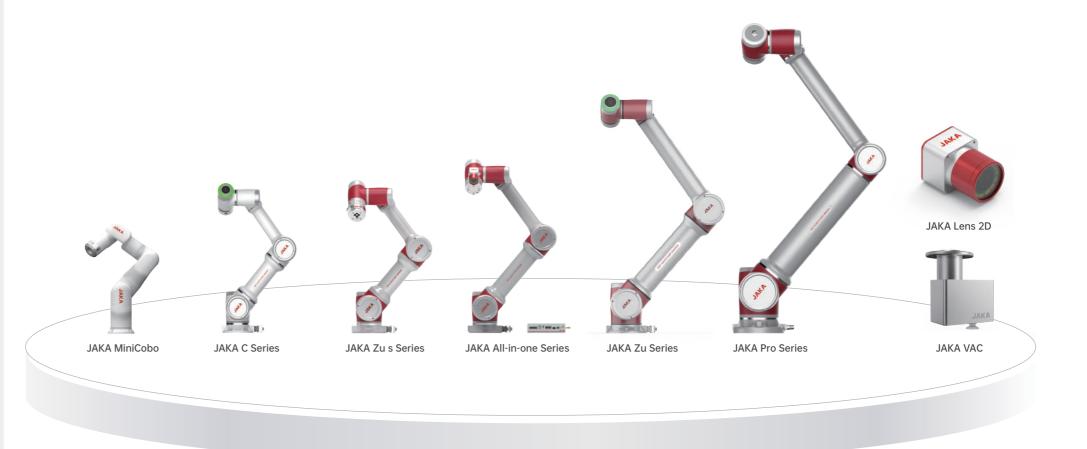


Global leader in flexible, intelligent cobots Ushering in a new generation in automation productivity

Easy to use

Reliable

Versatile



JAKA MiniCobo

Developing a technological ecosystem of depth, with experiment-led development



The JAKA Minicobo is compatible with Ethernet protocols (TCP/IP) and control interfaces such as Modbus and Profinet. It can simply and quickly integrate end effectors, grippers, suction, vision systems and force control modules. JAKA also provides an ROS package and SDK secondary development package, meaning that operators can quickly adapt the cobot to suit new or experimental applications.











ROS/SDK Deep Integration

- Support for ROS, providing full function package
- Rich secondary development capability and big data interaction interfaces
- SDK supports C, C++, C# and Python



Frictionless hardware-software ecosystem

- Full range of hardware-software pairing options
- Able to meet the needs of multiple educational and scientific research projects
- Support for TCP/IP, Modbus and Profinet protocols



Graphical programming intuitive learning

- Easy, wireless control and teach through the JAKA app
- Graphical programming and drag teach functionality
- Multiple active and passive safety mechanisms, ensuring the safety of man-machine collaboration

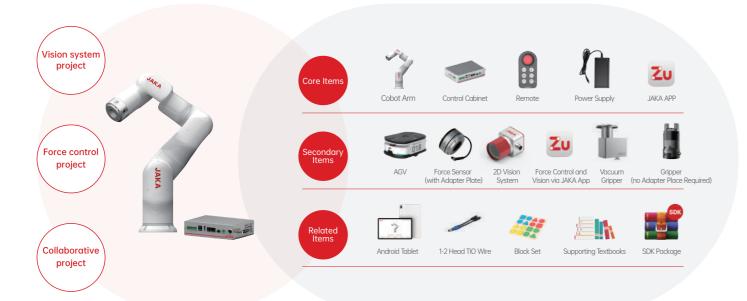


Supporting educational activities through versatility

- Detailed experimental teaching materials and operational instructions provided
- Means to combine typical industrial applications in classroom scenarios
- Can meet the needs of teaching at university-level, as well as professional scientific research









the talents of the future.

Scan QR for Stars Program introduction

'New Engineering' Construction

Based on an experimental teaching platform, the Stars Program focuses on typical application scenarios. As a platform, it has the advantages of being accessible, secure and open, while transferring skills and knowledge that are widely compatible with 'New Engineering'

The Stars Program teaching platform can be combined with other hardware and technical avenues, in order to create innovative platforms involving, for example, artificial intelligence, voice interaction, face recognition, EMG signal reading and more.

Innovative Platform Development

Competitions and Experimental Practice

The Stars Project combines typical industrial applications with teaching, developing practical skills as an integrated part of educational practice. At the same time, the teaching platform explores a rich interaction between software and hardware, so as to meet the needs of both teachers and students, and their independent experimental practice or pedagogy.

The versatile and wide-reaching software-hardware interactions that make up with Stars Program can inform the development of additional curriculums. The theoretical knowledge and practice guidance are applicable in courses on robotics, machinery, electrical engineering, computer science and more.

Curriculum Development

	Category	Vision Project	Force Control Project	Collaborative Project
Robot	Cobot	√	√	√
Vision	2D Vision	√	√	√
Force Control	6-Axis Force Sensor		√	√
Vacuum Gripper	Suction Cup	√	√	√
Gripper	Electric Gripper	√	√	√
Mobile Platform	AGV/ARM			√
	Tablet	√	√	√
Other	Block Set	√	√	√
	TIO Special Cable	√	√	√

Stars Program

Development in the Education Industry







Basic Cobot Teaching Platform



Platform Introduction

The Basic Cobot Teaching Platform is composed of a JAKA Minicobo module, a basic function module, a vision module and a computer learning module. It aims to combine theoretical knowledge learning with basic function practice, to enable the quick mastery in applying robotics knowledge. The platform is equipped with a complete curriculum, which can be applied in basic courses such as robot theory, machine vision, intelligent manufacturing and more.





☐ Platform Configuration

Cobot module

Basic function module

Vision module

Computer learning module



Platform advantages

- Operable via JAKA APP, with graphical and drag programming
- Combines theory with practice, to facilitate understanding and practical use skills
- Provides complete courses and routines, with best-practice examples, as access point for deeper robotics knowledge
- The integrated, customized design makes it perfect for use in a multimedia classroom
- Useable with any tablet, with a simple and intuitive operational interface



Experiments

Serial	Experiment
1	Robot cognition and assembly
2	Robot system settings
3	Basic robot operation
4	IO communication
5	Vision system and cognition
6	Vision system and communication
7	Parts sorting
8	Basic case study

Vision System Development Platform



Platform Introduction

The Vision System Development Platform is composed of a JAKA Minicobo module, a vision system module, and an end gripper. It is supported with an array of learning components, a complete curriculum and experimental scenarios. As an experimental teaching platform, it is suitable for professional practical teaching of robotics, automation, electronics, applied computer science and more.





Platform Configuration

Cobot module

Vision system



Platform advantages

- Operable via JAKA APP, with graphical and drag programming
- Wireless connection, with no teaching pendant
- Equipped with collision detection, it supports six levels of collision protection
- Rich communication interfaces supporting a variety of end effectors in plug-and-play
- Supports C, C++, C#, Python and ROS
- Can quickly establish a new vision application, with the help of colour and bar code recognition
- Capable of character recognition, measurement, calibration, alignment, image processing and more
- New scenarios can be quickly and easily established



Experiments

Serial	Experiment	
1	Safety operation procedures	
2	Collaborative robot cognition	
3	Use and control of teaching device	
4	Basic commands and position points	
5	IO point operations	
6	Vision system and cognition	
7	Industrial camera connection and calibration	
8	Edge contour extraction	
9	Bar code and QR code scanning	
10	LED lamp colour selection	
11	Dimension measurement of mechanical parts	
12	Vision system and communication	
13	Hand-eye calibration	
14	Bottle cap positioning and sorting	
15	Parts assembly	
16	Fixture design and adaptation	
17	Robot system integration	

Hybrid Cobot Development Platform



Platform Introduction

The Hybrid Cobot Development Platform combines the JAKA Minicobo with an AGV mobile platform. It is capable of simultaneous localization and mapping (SLAM), automatic navigation and obstacle avoidance. Equipped with a vision system, end effectors, force control sensors and more, it can complete experimental projects such as motion planning, visual grasping, and mobile material handling. It is an excellent educational and scientific research tool for robot technology, artificial intelligence, and intelligent manufacturing.





Platform Configuration

Cobot module

AGV module

Vision system (optional)

End effectors (optional)



Platform advantages

- Modular disassembly and assembly, adaptable according to application, object, or experiment
- Wide variety of available end effectors
- Equipped with SLAM capability, automatic navigation, obstacle avoidance, three-dimensional mapping and more advanced technology
- Integrated software supports the control of multiple modules in the same software
- Supports C, C++, C#, Python and ROS



Experiments

Serial	Experiment
1	ROS development environment
2	ROS message publishing and receiving
3	ROS service request and response
4	Gmapping algorithm, for map building and navigation
5	Robot movement control
6	Lidar use and position calibration
7	Autonomous navigation
8	Collaborative robot cognition
9	Basic cobot commands and position points
10	Vision system and communication
11	Hand-eye calibration











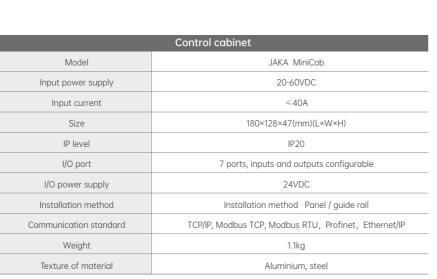








Control cabinet		
Model	JAKA MiniCab	
Input power supply	20-60VDC	
Input current	≤40A	
Size	180×128×47(mm)(L×W×H)	
IP level	IP20	
I/O port	7 ports, inputs and outputs configurable	
I/O power supply	24VDC	
Installation method	Installation method Panel / guide rail	
Communication standard	TCP/IP, Modbus TCP, Modbus RTU, Profinet, Ethernet/IP	
Weight	1.1kg	
Texture of material	Aluminium, steel	





Establishing a high-level training academy especially for the robot industry

Online & offline flexible teaching

Three training bases in Shanghai, Changzhou and Shenzhen

© Online lecture halls



10.000+

500+

10+





